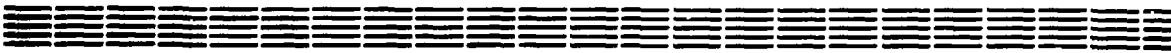


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ЕРЕВАНСКИЙ ФИЗИЧЕСКИЙ ИНСТИТУТ
YEREVAN PHYSICS INSTITUTE



D.R. KARAKHANYAN

INDUCED DIRAC OPERATOR AND SMOOTH
MANIFOLD GEOMETRY

ЦНИИатоминформ
ЕРЕВАН-1990

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**ԴԻՐԱԿԻ ՄԱԿԱԾՎԱԾ ՕՊԵՐԱՏՈՐԸ ԵՎ ՈՂՈՐԿ
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INDUCED DIRAC OPERATOR AND SMOOTH
MANIFOLD GEOMETRY

The determinant of the Dirac operator induced from arbitrary smooth manifold on Riemann surface is calculated explicitly.

Yerevan Physics Institute

Yerevan 1990

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Д.Р.КАРАХАНИЯ

ИНДУЦИРОВАННЫЙ ОПЕРАТОР ДИРАКА И ГЕОМЕТРИЯ
ГЛАДКИХ МНОГООБРАЗИЙ

Вычислен детерминант индуцированного из произвольного гладкого многообразия на двумерную поверхность оператора Дирака.

Ереванский физический институт

Ереван 1990

The induced Dirac operator emerged for the first time in Ref. [1] as a naive continuous limit of the three-dimensional Ising model. The determinant of the Dirac operator induced on surface Σ by spinor structure of \mathbb{R}^3 wherein Σ is embedded was calculated in Ref. [2]. This result was generalized for the \mathbb{R}^d case in Ref. [3].

Using the structure similarity between this theory and the Green-Schwarz superstring theory it turned out possible to apply the bosonization technique developed in Ref. [2] to the heterotic superstring theory [4].

In the present paper the result of [3] is generalized for the case of arbitrary smooth manifold M .

Let M be arbitrary smooth manifold wherein the two-dimensional surface Σ is embedded.

We shall be interested only in local properties of this embedding and not in global restrictions on it. Therefore we shall work in the limits of one coordinate vicinity on Σ with the coordinates S^α ($\alpha = 1, 2$) and one coordinate vicinity on M with the coordinates X^μ ($\mu = 1, \dots, d$).

By means of the tetrads $E_m^\mu(x)$:

$$E_\mu^m(x) \cdot E_\nu^m(x) = G_{\mu\nu}(x) \quad (1)$$

we can determine Dirac action in M :

$$S_D = \frac{i}{2} \int_M d^d X \cdot \sqrt{G} \cdot E_m^\mu (\bar{\psi} \gamma^m \partial_\mu \psi - \partial_\mu \bar{\psi} \gamma^m \psi) \quad (2)$$

which possesses local $SO(d)$ -invariance.

Here $G = \det \|G_{\mu\nu}\|$; $\psi(x)$ are the spinors of the space tangential to M ($SO(d)$ representation).

Let the surface Σ be described in M by the equation:

$$X^\mu = X^\mu(\xi^\alpha) \quad (3)$$

Then the projection $P: M \rightarrow \Sigma$ can be realized using the projective operator:

$$P^{\mu\nu} = \partial_\alpha X^\mu \cdot g^{\alpha\beta} \cdot \partial_\beta X^\nu \quad (4)$$

where $g^{\alpha\beta}$ is the metric induced from M on Σ :

$$g^{\alpha\gamma} \cdot g_{\gamma\beta} = \delta_\beta^\alpha, \quad g_{\alpha\beta} = \partial_\alpha X^\mu \cdot G_{\mu\nu} \cdot \partial_\beta X^\nu \quad (5)$$

The two-dimensional field theory of interest is obtained from (2) using projector (4):

$$S_{1D} = \frac{i}{2} \int_\Sigma d^2 \xi \cdot \sqrt{g} \cdot g^{\alpha\beta} \cdot \partial_\alpha X^\mu \cdot E_\mu^m (\bar{\psi} \gamma_m \partial_\beta \psi - \partial_\beta \bar{\psi} \gamma_m \psi) \quad (6)$$

Now we introduce the vectors tangential $\partial_\alpha X^\mu$ and normal n_i^μ ($i = 1, \dots, d-2$) to the surface:

$$\partial_\alpha X^\mu \cdot G_{\mu\nu} \cdot n_i^\nu = 0, \quad n_i^\mu \cdot G_{\mu\nu} \cdot n_j^\nu = \delta_{ij}, \quad i, j = 1, \dots, d-2 \quad (7)$$

Orthonormalizing the tangential vectors using two-dimensional tetrads

$$X_a^\mu(\xi) = e_a^\alpha(\xi) \cdot \partial_\alpha X^\mu(\xi), \quad e_a^\alpha(\xi) \cdot e_b^\beta(\xi) = g^{ab} \quad (8)$$

we obtain orthonormalized basis in each point of the surface:

$$(X_a^\mu, n_i^\mu) \quad (9)$$

With the use of local $SO(d)$ -rotation the basis (9) in every point of Σ can be reduced to some fixed form $(\overset{0}{X}_a^\mu, \overset{0}{n}_i^\mu)$ independent of ξ^α .

Or in the spinor representation:

$$\begin{aligned} \gamma_a(\xi) &= X_a^m(\xi) \cdot \gamma_m = \Omega^{-1}(\xi) \sigma_a \Omega(\xi) \\ \gamma_i(\xi) &= n_i^m(\xi) \cdot \gamma_m = \Omega^{-1}(\xi) \sigma_i \Omega(\xi) \end{aligned} \quad (10)$$

where $X_a^m = X_a^\mu \cdot E_\mu^m$
 $n_i^m = n_i^\mu \cdot E_\mu^m$

and (σ_a, σ_i) is some fixed basis of d -dimensional Dirac γ -matrices which differs from γ_m in no more than global rotation.

From (10) we can readily obtain:

$$\begin{aligned} \Omega^{-1} d\Omega &= \frac{1}{4} (\gamma_a d\gamma^a + \gamma_i d\gamma^i) = \\ &= \frac{1}{4} \Gamma^{ab} \gamma_{ab} + \frac{1}{2} h^{ai} \gamma_{ai} + \frac{1}{4} H^{ij} \gamma_{ij} \end{aligned} \quad (11)$$

where Γ , h and H fields are defined as expansion coefficients of $d\gamma^a$ and $d\gamma^i$ over basis (10):

$$\begin{aligned} d\gamma^a &= \Gamma^{ab} \gamma_b + h^{ai} \gamma_i \\ d\gamma^i &= -h^{ai} \gamma_a + H^{ij} \gamma_j \end{aligned} \quad (12)$$

The integrability conditions of system (12) provide the condition of embedding of Σ in M in terms of Γ , h and H fields:

$$\begin{aligned} d\Gamma^{ab} &= -h^{ai} \cdot h^{bi} \\ dh^{ai} &= -\Gamma^{ab} h^{bi} - H^{ij} h^{aj} \\ dH^{ij} - H^i_k H^{kj} &= -h^{ai} \cdot h^{aj} \end{aligned} \quad (13)$$

Differentiating the (5) we can readily obtain a relation:

$$\nabla_\alpha (\partial_\beta X^\mu) = h_{\alpha\beta}^i \cdot n_i^\mu \quad (14)$$

which defines a symmetric second quadratic form of the surface $h_{\alpha\beta}^i$. Here the covariant derivative affects both curved indices α and μ .

The fields defined by expansion (12)

$$\begin{aligned}
 \Gamma_{\alpha}^{ab} &= \frac{1}{\hbar_2} \cdot \hbar_2 (\gamma^b \cdot \partial_{\alpha} \gamma^a) = e_{\beta}^b \nabla_{\alpha} e^{\beta} \cdot \omega_{\alpha}^{mn} X_m^a X_n^b \\
 h_{\alpha}^{ai} &= \frac{1}{\hbar_2} \cdot \hbar_2 (\gamma^i \cdot \partial_{\alpha} \gamma^a) = e^{\beta a} h_{\alpha\beta}^i - \omega_{\alpha}^{mn} X_m^a \cdot n_n^i \\
 H_{\alpha}^{ij} &= \frac{1}{\hbar_2} \cdot \hbar_2 (\gamma^j \cdot \partial_{\alpha} \gamma^i) = n_{\mu}^j \cdot \partial_{\alpha} X^{\mu} \cdot \nabla_{\nu} n^{\mu i} - \omega_{\alpha}^{mn} n_m^i n_n^j
 \end{aligned} \tag{15}$$

differ from the $\Gamma^{(e)}$, $h^{(e)}$ and $H^{(e)}$ fields corresponding to them in the case $M = R^d$ only by one term which contains spinor connection of space M , $\omega_{\alpha}^{mn} = \partial_{\alpha} X^{\nu} \cdot E_{\mu}^{\nu} \cdot \nabla_{\nu} E^{\mu m}$, the presence of which in the action reflects its local $SO(d)$ -symmetry.

The relation (11) can be rewritten in the form:

$$d\Omega \cdot \Omega^{-1} = d\Omega^{(e)} \cdot \Omega^{(e)-1} - \frac{1}{4} \omega^{mn} \cdot \Omega \gamma_{mn} \Omega^{-1} \tag{16}$$

which makes the relationship between the case $M = R^d$ and the general case explicit.

The induced Dirac operator corresponding to the action (6):

$$D = i e_{\alpha}^a \Omega^{-1} \sigma^a \left(\partial_{\alpha} - \frac{1}{4} \Gamma_{\alpha}^{bc} \sigma_{bc} - \frac{1}{4} H_{\alpha}^{ij} \sigma_{ij} \right) \Omega + \frac{i}{8} e_{\alpha}^a \omega_{\alpha}^{mn} \{ \gamma^a, \gamma^{mn} \} \tag{17}$$

The last term due to which D differs from the Dirac operator considered in Ref. [3] does not allow to write the action (6) in the form of two-dimensional field theory of fermions interacting with the gravitation and gauge field.

From (17) we can see that along with the reparametrizational

and local $SO(d)$ invariances the action also possesses the local $SO(2) \times SO(d-2)$ invariance acquired just as in the $M=R^d$ case owing to the transition from X^μ to Γ , h and H fields.

Indeed, in Ref. [3] we had the action $\frac{i}{2} \int d^d x \sqrt{g} g^{\mu\nu} \partial_\alpha \lambda^i \cdot (\bar{\psi} \gamma_\mu \partial_\beta \psi - \partial_\beta \bar{\psi} \gamma_\mu \psi)$ where $g_{\alpha\beta} = \partial_\alpha X^\mu \cdot \partial_\beta X^\mu$, i.e. d independent bosonic degrees of freedom combined in a reparametrization-invariant way. To integrate over ψ we reduced it to the form $\int d^d x \sqrt{g} \bar{\psi} \hat{D} \psi$ where $\hat{D} = i \not{e}^{\alpha a} \Omega^{-1} (\not{\partial}_\alpha - \frac{1}{4} \Gamma^{bc} \not{\sigma}_{bc} - \frac{1}{4} H_\alpha^{ij} \not{\sigma}_{ij}) \Omega$. The $d-2$ bosonic degrees of freedom are distributed between e_α^a , Γ_α^{ab} , h_α^{ai} and H_α^{ij} fields with respect to symmetricity of $h_{\alpha\beta}^i = h_{\beta\alpha}^i$ and integrability conditions as well as the action symmetries in these variables as follows:

$$4 + 2 + 3(d-2) + (d-2)(d-3) - \frac{d(d-1)}{2} - 1 - \frac{(d-2)(d-3)}{2} - 2 - 2 = d-2$$

The similar calculation in the case of arbitrary manifold for the action (6) gives:

$$d^2 + d - \frac{d(d-1)}{2} - 2$$

Similarly d quantities X^μ are replaced by

$$4 + 3(d-2) + (d-2)(d-3) - \frac{d(d-1)}{2}$$

of quantities e_α^a , $h_{\alpha\beta}^i$, ($\Gamma_\alpha^{ab} = e_\beta^b \nabla_\alpha e^{\beta a}$), H_α^{ij} constrained by $\frac{1}{2} d(d-1)$ integrability conditions and local $SO(2) \times SO(d-2)$ symmetry.

If now we substitute in (17) the expansion

$$\gamma_m = X_m^a \cdot \gamma_a + h_m^i \cdot \gamma_i \tag{18}$$

and use a $\frac{SO(d)}{SO(2) \times SO(d-2)}$ coset-part of local $SO(d)$ -symmetry for imposition of gauge condition, we'll have:

$$e^{\alpha a} \omega_{\alpha}^{mn} X_m^b \cdot n_n^i = e^{\alpha b} \omega_{\alpha}^{mn} X_m^a n_n^i \quad (19)$$

This is possible because at $SO(d)$ rotations

$$\gamma_a \rightarrow W(\xi) \gamma_a W(\xi), \quad \gamma_i \rightarrow W(\xi) \gamma_i W(\xi), \quad \Omega \rightarrow \Omega(\xi) W(\xi)$$

i.e.

$$\Omega^T d\Omega \rightarrow W^{-1}(\Omega^T d\Omega + dW \cdot W^{-1}) W$$

and choosing $dW \cdot W^{-1} = W^{\alpha i} \cdot \frac{1}{2} \gamma_{\alpha i} \in \frac{SO(d)}{SO(2) \times SO(d-2)}$

we can attain that the expression $(h_{\alpha}^{ai} + W_{\alpha}^{ai}) \cdot e^{\alpha b}$ would be symmetric over α, b , which corresponds to gauge condition (19) if we recall equation (14).

In gauge (19) the action (6) takes a form usual for two-dimensional field theory:

$$S_{1D} = i \int d^2 x \sqrt{g} e_{\alpha}^{\mu} \bar{\psi} \Omega^{-1} \sigma^{\alpha} \left(\partial_{\mu} - \frac{1}{4} e_{\beta}^{\nu} \gamma_{\nu} e^{\beta b} \sigma_b - \frac{1}{4} H_{\alpha}^{ij} \sigma_{ij} \right) \psi \quad (20)$$

The Dirac operator corresponding to (20) anticommutes with matrix γ_{+-} , therefore the left- and right-side fermions in (20) separate from each other.

We parametrize the tetrads in the form:

$$e_{\alpha}^a \cdot \sigma_a = \rho^{1/2} \cdot d_{\alpha} f^a \cdot \lambda^1 \sigma_a \quad (21)$$

To calculate the actions of the left fermions we fix reparametrizational invariance by imposing conformal gauge:

$$g_{\alpha\beta}(\xi) = \rho(\xi) \cdot \delta_{\alpha\beta} \quad \text{or} \quad \begin{aligned} \hat{e}^+ &= e^+_{\alpha} \cdot \sigma^{\alpha} = \rho^{-1/2} \cdot \lambda^{\dagger} \sigma^+ \lambda \\ \hat{e}^- &= e^-_{\alpha} \cdot \sigma^{\alpha} = \rho^{-1/2} \cdot \lambda^{\dagger} \sigma^- \lambda \end{aligned} \quad (22)$$

The Dirac operator in gauge (22):

$$D = i \Omega^{\dagger} \lambda^{\dagger} \rho^{-3/4} [\sigma_- (\partial_+ + H_+) + \sigma_+ (\partial_- + H_-)] \rho^{3/4} \lambda \Omega = D_L + D_R \quad (23)$$

where $H_{\pm} = -\frac{1}{4} H_{\alpha}{}^{\beta} \sigma_{ij}$.

Now we define variation of determinant of Dirac chiral operator:

$$\begin{aligned} \delta W &= \delta \log \det D_L = \lim_{\epsilon \rightarrow 0} \text{F.P.} \int_{\Sigma} ds \text{Tr} (\delta D_L \cdot D_R \hat{e}^{-\epsilon D_L D_R}) \\ &= \lim_{\epsilon \rightarrow 0} \text{F.P.} \text{Tr} \left[(\Omega^{\dagger} \delta \Omega + \Omega^{\dagger} \lambda^{\dagger} \delta \lambda \Omega + \Omega^{\dagger} \dot{g}^{\dagger} \delta g \Omega + \frac{1}{4} \delta \log \rho) \hat{e}^{-\epsilon D_R D_L} \right. \\ &\quad \left. + (-\Omega^{\dagger} \delta \Omega - \Omega^{\dagger} \lambda^{\dagger} \delta \lambda \Omega - \Omega^{\dagger} \dot{g}^{\dagger} \delta g \Omega - \frac{3}{4} \delta \log \rho) \hat{e}^{-\epsilon D_L D_R} \right] \end{aligned} \quad (24)$$

wherein we parametrized

$$H_{\pm} = \dot{g}^{\dagger} \partial_{\pm} g \quad (25)$$

From here the Ward identities for effective action are

$$\begin{aligned} \delta W &= -\frac{1}{4\pi} \int_{\Sigma} d^2x \partial_2 (\delta \Omega \cdot \Omega^{\dagger} (\Gamma_+^{(0)} + H_+)) - \frac{1}{4\pi} \int_{\Sigma} d^2x \partial_2 (H_+ \dot{g}^{\dagger} \delta g) \\ &\quad - \frac{1}{4\pi} \int_{\Sigma} \partial_2 (\Gamma_+ \lambda^{\dagger} \delta \lambda) + \frac{\partial_2 \mathbb{1}}{48\pi} \int_{\Sigma} d^2x \partial_2 \log \rho \cdot \delta \log \rho \end{aligned} \quad (26)$$

To integrate equation (26) we impose a gauge condition fixing $SO(2) \times SO(d-2)$ local invariance:

$$\partial_+ \Gamma_-^{ab} + \partial_- \Gamma_+^{ab} = \partial_+ H_-^{ij} + \partial_- H_+^{ij} = 0 \quad (27)$$

The integrable expression corresponding to the first term in (26) is

$$\frac{1}{24\pi} \delta \int_{\Sigma_t} t_2 (\delta \Omega \cdot \Omega^{-1})^3 = -\frac{1}{8} \int_{\Sigma_t} t_2 (\delta \Omega \cdot \Omega^{-1} (\Gamma_+ + H_+))$$

where Σ_t is a three-dimensional region in M with surface Σ as a boundary.

Using the integrability conditions of (13) we can readily show that

$$\int_{\Sigma_t} t_2 (\delta \Omega \cdot \Omega^{-1})^3 = -\frac{3}{8} t_2 \int_{\Sigma_t} (\Gamma^{ab} d\Gamma_{ab} + H^{ij} (dH_{ij} - \frac{2}{3} H_{ik} H_{kj}))$$

A final expression for effective action of the left fermions will be

$$\begin{aligned} W = & \frac{t_2}{192\pi} \int_{\Sigma} d^5 \left[\sqrt{g} (\Gamma_{\alpha}^{\omega} - \lambda^{\omega} \partial_{\alpha} \lambda) g^{\alpha\beta} (\Gamma_{\beta}^{\omega} - \lambda^{\omega} \partial_{\beta} \lambda) - \right. \\ & \left. - 2 \epsilon^{\alpha\beta} \Gamma_{\alpha}^{\omega} \cdot \lambda^{\omega} \partial_{\beta} \lambda \right] + \frac{t_2}{96\pi} \int_{\Sigma} \left[\Gamma^{ab} d\Gamma_{ab} + \right. \\ & \left. + H^{ij} (dH_{ij} - \frac{2}{3} H^2)_{ij} \right] + \frac{1}{8\pi} \int_{\Sigma} d^5 \sqrt{g} g^{\alpha\beta} t_2 (H_{\alpha} H_{\beta}) \\ & + \frac{1}{4\pi} \left[\frac{1}{2} \int_{\Sigma} d^5 \sqrt{g} g^{\alpha\beta} t_2 (g^{\gamma} \partial_{\alpha} g \cdot g^{\gamma} \partial_{\beta} g) - \frac{i}{3} \int_{\Sigma} t_2 (g^{\gamma} dg)^3 \right] \end{aligned} \quad (28)$$

The last two lines appear in case $\dim M > 3$. The first two lines, according to Ref. [5] interpretation, define a new covariant local action of two-dimensional gravitation.

Except for the first three terms all the rest are modified by the contribution of d-dimensional spinor connection compared to the $M = R^d$ case.

In view of the necessity of compactification of "superfluous" space measurements in superstring theory, the problem of quantization of superstrings propagating in arbitrary smooth manifold is highly urgent.

As far as the theory of induced Dirac action is a simplified model of string theory (see Ref.[4]), the present work seems to be promising in this direction.

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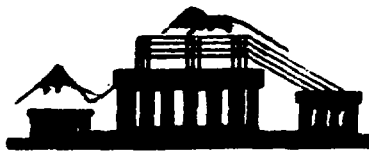
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